Amendments to the Specification:

Please amend the fourth paragraph bridging pages 10 and 11 as follows:

The position detecting control unit 3 is provided, as shown in FIG. 3, <u>with</u> a position detecting control unit 3c for capturing signals from unillustrated GPS satellites and calculating the position of the hydraulic excavator, a storage unit 3b for storing the thus-detected position information and a preset operable area for the hydraulic excavator, and a control unit 3a for performing transmissions/receptions of signals with the main controller 2, reading results of a detection by the position detecting unit 3c, and performing processing to store the results of the detection in the storage unit 3b.

Please amend the third paragraph bridging pages 11 and 12 as follows:

In this state, the position detecting unit 3c which ~~constructs~~ <u>instructs</u> the position detecting control unit 3, no matter whether or not there is an instruction signal from the control unit 3a, calculates the current position of the hydraulic excavator from signals from the GPS satellites upon capturing the signals, and outputs the results to the control unit 3a. The control unit 3a compares the inputted current position with the operable area stored in the storage unit 3b and, when the current position departs from the operable area, outputs

information on the current position and a theft signal to the main controller 2.

Please amend the second paragraph on page 14 as follows:

In Step S5, a current time T1 is read from the clock ~~unit 2b~~ unit 2c, and in the next Step S6, a determination is made as to whether or not a predetermined time Ts, for example, 3 hours or so have elapsed from the input of the stop signal of the engine 7. If not determined to have elapsed, the routine moves to Step S7.

Please amend the fourth paragraph bridging pages 16 and 17 as follows:

In Step S23, an instruction signal is outputted to turn on the switch 9 which has been in the turned-off position. As a result, power is fed to the position detecting control unit 3, and at the position detecting control unit 3, the position is detected and the current position information (X1,Y1) is outputted to the main controller 2.